## 

 shopm ch cu trioc Peysitists


## Outline

6.4 Discrete signal
6.4.1 Sampling theorem
6.4.2 Pulse amplitude modulation (PAM)
6.4.3 Discrete Fourier transform
6.4.4 z-transform
6.4.5 Transfer function of discrete time signal

Ch. 7 Digital signals and circuits
7.2 Logic gates
7.3 Implementation of logic gates
7.4 Circuit implementation and simplification of logic operation

## 6．4 Discrete signal

## 6．4．1 Sampling theorem

Sampled signal $\quad \tilde{x}(t)=x(t) \delta_{\tau}(t)$



Isao Someya 1915－2007


Claude Shannon 1916－2001

1928 H．Nyquist 1949 C．Shannon染谷勲


### 6.4.1 Sampling theorem

$$
\begin{aligned}
\delta_{\tau}(t) & =\sum_{j=-\infty}^{\infty} \delta(t-j \tau)=\sum_{n=-\infty}^{\infty}\left[\frac{1}{\tau} \int_{-\pi / \tau}^{\pi / \tau} \delta(s) d s\right] \exp \left(-i n \frac{2 \pi}{\tau} t\right) \\
& =\frac{1}{\tau} \sum_{n=-\infty}^{\infty} \exp \left(-i n \frac{2 \pi}{\tau} t\right) \\
\mathscr{F}\left\{\delta_{\tau}(t)\right\} & =\int_{-\infty}^{\infty}\left[\frac{1}{\tau} \sum_{-\infty}^{\infty} e^{-i n(2 \pi / \tau) t}\right] e^{i \omega t} d t=\frac{1}{\tau} \sum_{n=-\infty}^{\infty} \int_{-\infty}^{\infty} \exp \left[i\left(\omega-n \frac{2 \pi}{\tau}\right) t\right] d t \\
& =\frac{2 \pi}{\tau} \sum_{n=-\infty}^{\infty} \delta\left(\omega-n \frac{2 \pi}{\tau}\right)=\frac{2 \pi}{\tau} \delta_{2 \pi / \tau}(\omega)
\end{aligned}
$$

$$
\mathscr{F}\{x(t)\}=X(\omega), \mathscr{F}\left\{\tilde{x}_{\tau}(t)\right\}=\tilde{X}_{\tau}(\omega)
$$

$$
\tilde{X}_{\tau}(\omega)=\frac{1}{2 \pi} X(\omega) * \frac{2 \pi}{\tau} \delta_{2 \pi / \tau}(\omega)=\frac{1}{\tau} X(\omega) * \sum_{n=-\infty}^{\infty} \delta\left(\omega-n \frac{2 \pi}{\tau}\right)
$$

$$
=\frac{1}{\tau} \int_{-\infty}^{\infty} X\left(\omega^{\prime}\right)\left\{\sum_{n=-\infty}^{\infty} \delta\left(\omega-n \frac{2 \pi}{\tau}-\omega^{\prime}\right)\right\} d \omega^{\prime}=\frac{1}{\tau} \sum_{n=-\infty}^{\infty} X\left(\omega-n \frac{2 \pi}{\tau}\right)
$$

### 6.4.1 Sampling theorem



### 6.4.1 Sampling theorem: Reconstructing signal



$$
\begin{aligned}
x(t) & =\tau \frac{1}{\tau} \operatorname{sinc}\left(\frac{t}{\tau}\right) * \tilde{x}_{\tau}(t)=\operatorname{sinc}\left(\frac{t}{\tau}\right) * \sum_{n=-\infty}^{\infty} x(t) \delta(t-n \tau) \\
& =\int_{-\infty}^{\infty} \operatorname{sinc}\left(\frac{s}{\tau}\right) \sum_{n=-\infty}^{\infty} x(t-s) \delta(t-n \tau-s) d s=\sum_{n=-\infty}^{\infty} \operatorname{sinc}\left(\frac{t-n \tau}{\tau}\right) x(n \tau)
\end{aligned}
$$

### 6.4.2 Pulse amplitude modulation (PAM)




$$
s(t)=f(t) \delta_{\tau}(t)=\sum_{n=-\infty}^{\infty} f(t) \delta(t-n \tau)
$$

Demodulation $=$ Reconstruction of continuous signal from sampled data.

$$
f(t)=\mathscr{F}^{-1}\left\{P_{\pi / \tau}(\omega) \mathscr{F}\{s(t)\}\right\}
$$

## Demodulation of PAM and a trick in the sampling theore

In the sampling theorem, though we only have discrete-time data, we can reconstruct complete original signal.

## $\uparrow$

Assumption: we have data in infinite period $[-\infty,+\infty]$.

However in actual situations we can never have such data.

Need to consider handling data in a finite period.

### 6.4.3 Discrete Fourier transform




Assumption:
$F(\omega)=\mathscr{F}\{f(t)\}$, not zero in $\omega \in\left(-\frac{\pi}{\tau}, \frac{\pi}{\tau}\right)$

$$
N=\frac{\zeta}{\tau} \in \mathbb{N}
$$

can be assumed without loosing generality

$$
\breve{f}(t)=\sum_{n=-\infty}^{\infty} f(t-n \zeta), \quad \breve{F}(\omega)=\sum_{n=-\infty}^{\infty} F\left(\omega+n \frac{2 \pi}{\zeta}\right)
$$

$$
\left(\breve{f}(t)=\left(f * \delta_{\zeta}\right)(t)=\sum_{n=-\infty}^{\infty} \int_{-\infty}^{\infty} f(\xi) \delta(t-n \zeta-\xi) d \xi\right)
$$

Fourier expansion: $\quad \breve{f}(t)=\frac{1}{\zeta} \sum_{n=-\infty}^{\infty} F\left(n \frac{2 \pi}{\zeta}\right) \exp \left(2 n \pi i \frac{t}{\zeta}\right)$

### 6.4.3 Discrete Fourier transform

$$
\begin{gathered}
n=l+m N \quad \sum_{n=-\infty}^{\infty} \rightarrow \sum_{l=0}^{N-1} \sum_{m=-\infty}^{\infty} \quad t=j \tau \quad j \in \mathbb{Z} \\
\begin{aligned}
& \breve{f}(j \tau)=\frac{1}{\zeta} \sum_{l=0}^{N-1} \sum_{m=-\infty}^{\infty} F\left[(l+m N) \frac{2 \pi}{\zeta}\right] \exp \left[(l+m N) 2 \pi i \frac{j \tau}{\zeta}\right] \\
&=\frac{1}{N \tau} \sum_{l=0}^{N-1} \sum_{m=-\infty}^{\infty} F\left(\frac{2 \pi l}{\zeta}+m \frac{2 \pi}{\tau}\right) \exp \left(2 \pi i \frac{l j}{N}\right) \\
&= \frac{1}{N \tau} \sum_{l=0}^{N-1} \breve{F}\left(l \frac{2 \pi}{\zeta}\right) \exp \left(2 \pi i \frac{l j}{N}\right) \\
& \text { Twiddle factor: } W_{N} \equiv \exp \left(-i \frac{2 \pi}{N}\right) \\
& \eta \equiv \frac{2 \pi}{\zeta} \quad \breve{f}(j \tau)=\frac{1}{N \tau} \sum_{l=0}^{N-1} \breve{F}(l \eta) W_{N}^{-l j}
\end{aligned}
\end{gathered}
$$

### 6.4.3 Discrete Fourier transform

$$
\forall n, m \in \mathbb{Z} \quad W_{N}^{n+m N}=W_{N}^{n},
$$

Twiddle factor:

$$
\frac{1}{N} \sum_{n=0}^{N-1} W_{N}^{n m}= \begin{cases}1 & \text { for } \quad m=0 \\ 0 & \text { for } \quad m \neq 0\end{cases}
$$

$$
\tau \sum_{j=0}^{N-1} \breve{f}(j \tau) W_{N}^{m j}=\sum_{j=0}^{N-1}\left[\frac{1}{N} \sum_{l=0}^{N-1} \breve{F}(l \eta) W_{N}^{(m-l) j}\right]=\breve{F}(m \eta)
$$

$$
f_{n} \equiv \breve{f}(n \tau), \quad F_{k} \equiv \frac{1}{\tau} \breve{F}(k \eta)
$$

Discrete Fourier transform:

$$
F_{k}=\sum_{n=0}^{N-1} f_{n} W_{N}^{k n},
$$

(DFT)

$$
f_{n}=\frac{1}{N} \sum_{k=0}^{N-1} F_{k} W_{N}^{-k n} .
$$

### 6.4.3 Discrete Fourier transform

$$
\begin{gathered}
\boldsymbol{F}={ }^{t}\left\{F_{i}\right\}, \boldsymbol{W}=\left\{W_{N}^{i j}\right\}, \boldsymbol{f}={ }^{t}\left\{f_{i}\right\} \\
\boldsymbol{F}=\boldsymbol{W} \boldsymbol{f}, \quad \boldsymbol{f}=\frac{1}{N} \boldsymbol{W}^{*} \boldsymbol{F} \\
{ }^{t} \boldsymbol{W}^{*} \boldsymbol{W}=N \boldsymbol{I}_{N} \quad \text { i.e., } \frac{1}{\sqrt{N}} \boldsymbol{W}: \text { unitary }
\end{gathered}
$$

### 6.4.4 z-transform

Discrete Laplace transform: z-transform

$$
\begin{gathered}
\tilde{f}_{\tau}(t)=\sum_{n=0}^{\infty} f(n \tau) \delta(t-n \tau) \quad(t \geq 0) \\
\mathscr{L}\left\{\tilde{f}_{\tau}(t)\right\}(s)=\mathscr{L}\left\{\sum_{n=0}^{\infty} f(n \tau) \delta(t-n \tau)\right\} \\
=\sum_{n=0}^{\infty} f(n \tau) \mathscr{L}\{\delta(t-n \tau)\}=\sum_{n=0}^{\infty} f(n \tau) \exp (-s n \tau) \\
z=\exp (s \tau), f_{n}=f(n \tau), F(z)=\mathscr{L}\left\{\tilde{f}_{\tau}(t)\right\}
\end{gathered}
$$

$$
F(z)=\sum_{n=0}^{\infty} f_{n} z^{-n}=\mathscr{Z}\left[\tilde{f}_{\tau}(t)\right]
$$

### 6.4.4 z-transform

| $f_{n}$ | $F(z)$ | conversion area |
| :---: | :---: | :--- |
| $\delta(n)$ | $\frac{1}{1-z^{-1}}$ | $z$-plane |
| 1 | $\frac{z^{-1}}{\left(1-z^{-1}\right)^{2}}$ | $\|z\|>1$ |
| $n$ | $\left(-z \frac{d}{d z}\right)^{k} \frac{1}{1-z^{-1}}$ | $\|z\|>1$ |
| $n^{k}$ | $\frac{1}{1-a z^{-1}}$ | $\|z\|>1$ |
| $a^{n}$ | $\frac{\sin (\omega \tau) z^{-1}}{1-2 \cos (\omega \tau) z^{-1}+z^{-2}}$ | $\|z\|>1$ |
| $\sin (n \omega \tau)$ | $\frac{1-e^{-\alpha \tau} \cos (\omega \tau) z^{-1}}{1-2 e^{-\alpha \tau} \cos (\omega \tau) z^{-1}+e^{-2 \alpha \tau} z^{-2}}$ | $\|z\|>e^{-\alpha \tau}$ |

### 6.4.4 z-transform

| Property | Signal | z-transform |
| :--- | :---: | :---: |
| linearity | $a f_{n}+b g_{n}$ | $a F(z)+b G(z)$ |
| z-domain scaling | $f_{\alpha n}$ | $F\left(z^{1 / \alpha}\right)$ |
| time shift | $f_{n+k}$ | $z^{k}\left[F(z)-\sum_{l=0}^{k-1} f(l) z^{l}\right]$ |
| time shift II | $f_{n-k}$ | $z^{-k} F(z)$ |
| scaling | $e^{\mp \alpha n} f_{n}$ | $F\left(e^{ \pm \alpha} z\right)$ |
| scaling II | $a^{n} x_{n}$ | $-z\left(a^{-1} z\right)$ |
| product with index | $n f_{n}$ | $\left(z \frac{d}{d z} F(z)\right.$ |
| differentiation | $n^{k} f_{n}$ | $\left(-z \frac{d}{d z}\right)^{n} F(z)$ |
| integration | $\frac{f_{n}}{n+a}$ | $z^{a} \int_{z}^{\infty} \xi^{-a+1} F(\xi) d \xi$ |
| convolution | $f_{n} * g_{n}$ | $F(z) \cdot G(z)$ |
| product | $f_{n} \cdot g_{n}$ | $\frac{1}{2 \pi i} \oint_{c} F(\xi) G\left(\frac{z}{\xi}\right) \xi^{-1} d \xi$ |

### 6.4.5 Transfer function for discrete time signal

$$
\tilde{f}_{\tau}(t)=f(t) \delta_{\tau}(t)=\sum_{k=-\infty}^{\infty} f_{k} \delta(t-k \tau)
$$

$h_{n}$ : (impulse) response to $\delta(n \tau)$, response to discrete signal $f_{n}=f(n \tau)$

$$
\begin{aligned}
& g_{n}=\mathscr{R}\left\{\tilde{f}_{\tau}(n \tau)\right\}=\mathscr{R}\left\{\sum_{k^{\prime}=-\infty}^{\infty} f\left(k^{\prime} \tau\right) \delta\left[\left(n-k^{\prime}\right) \tau\right]\right\} \\
&=\sum_{k^{\prime}=-\infty}^{\infty} f_{k^{\prime}} h_{n-k^{\prime}}=\sum_{k=-\infty}^{\infty} h_{k} f_{n-k} \\
& G(z)=\mathscr{Z}\left[g_{n}\right]=\mathscr{Z}\left[\sum_{k=0}^{\infty} h_{k} f_{n-k}\right]=\sum_{n=0}^{\infty}\left(\sum_{k=0}^{\infty} h_{k} f_{n-k}\right) z^{-n} \\
&=\sum_{k=0}^{\infty} h_{k} \sum_{n=0}^{\infty} f_{n-k} z^{-n}=\sum_{k=0}^{\infty} h_{k} z^{-k} F(z) \\
& H(z)=\mathscr{Z}\left[h_{n}\right]=\sum_{k=0}^{\infty} h_{k} z^{-k} \quad: \text { Transfer function } \\
& G(z)=H(z) F(z)
\end{aligned}
$$

## Crystal lattice and X-ray diffraction



Max von Laue
1879-1960
Laue pattern

Diamond lattice

[100]
[111]

## Optical Frequency Comb

## Optical Frequency Comb

beam splitter

beat note
detector

$\longrightarrow$ frequency

## Frequency Comb



## Measurement of the Doppler effect in cosmic expansion



## Byzantine mosaic

## Chapter 7

## Digital signal and circuits

Chartres Blue (Stained glass)


## Ch. 7 Digital signal and circuits



Value discretized $\rightarrow$ Digital signal
Signal unit : 0 xor 1 (bit)
Boolean algebra: F xor T
Voltage level : L xor H

Multiple bit $\rightarrow$ binary operation $\rightarrow$ parallel signal

### 7.2 Logic gates

Digital signal=logic value $\rightarrow$ Logic operation : logic gates
De Morgan's laws: $\overline{x+y}=\bar{x} \cdot \bar{y}, \overline{x \cdot y}=\bar{x}+\bar{y}$

| input |  |  |  |  |  |  | output |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $t_{1}$ | $t_{2}$ | $\cdots$ | $t_{m}$ |  | $t_{1}$ | $t_{2}$ | $\cdots$ | $t_{m}$ |  |
| Ch. | 1 | 0 | 1 | $\cdots$ | $f_{1 m}$ | 1 | 1 | 1 | $\cdots$ | $q_{1 m}$ |  |
|  | 2 | 1 | 0 | $\cdots$ | $f_{2 m}$ | 2 | 0 | 1 | $\cdots$ | $q_{2 m}$ |  |
|  | $\vdots$ | $\vdots$ | $\vdots$ | $\ddots$ | $\vdots$ | $\vdots$ | $\vdots$ | $\vdots$ | $\ddots$ | $\vdots$ |  |
|  | $n$ | 0 | 1 | $\cdots$ | $f_{n m}$ | $l$ | 0 | 1 | $\cdots$ | $f_{l m}$ |  |

Combinational logic $\rightarrow$ Truth table
Sequential logic $\rightarrow$ Timing chart


### 7.2.2 Combinational logic: Double input gates

| input1 | input 2 | and | or | xor | nand |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 0 | 0 | 1 |
| 1 | 0 | 0 | 1 | 1 | 1 |
| 0 | 1 | 0 | 1 | 1 | 1 |
| 1 | 1 | 1 | 1 | 0 | 0 |


and

nand

or

nor

xor

RS (reset-set) Flip-Flop (FF)

Truth table

| S | R | Q | $\overline{\mathrm{Q}}$ | Response |
| :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | Q | $\overline{\mathrm{Q}}$ | no change |
| 0 | 1 | 0 | 1 | reset |
| 1 | 0 | 1 | 0 | set |
| 1 | 1 | undetermined |  |  |

Symbol


Equivalent circuit with discrete gates


### 7.2.3 Sequential logic: Flip-Flop (FF)

JK Flip-Flop

| J | K | Q | Q for the next CLK |
| :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 0 |
| 0 | 0 | 1 | 1 |
| 0 | 1 | - | 0 |
| 1 | 0 | - | 1 |
| 1 | 1 | 0 | 1 |
| 1 | 1 | 1 | 0 |

Symbol


Equivalent circuit with discrete gates


### 7.2.3 Sequential logic: D-FF, T-FF



Truth table



### 7.2.4 Sequential logic: Counters

Unsynchronized counter (ripple counter)


Timing chart


### 7.2.4 Sequential logic: Counters

Synchronized counter
Equivalent circuit with discrete gates


Timing chart


### 7.3 Implementation of logic gates

NAND gates


TTL (transistor-transistor logic)
CMOS (complimentary MOS)

### 7.3 Implementation of logic gates

LT Spice simulation

盽 Draft1.raw



### 7.3 Implementation of logic gates

Voltage levels diagram


## TTL logic family evolution



Legacy: don't use
Widely used today in new designs

## CMOS logic family evolution

obsolete


## General trend:

- Reduction of dynamic losses through successively decreasing supply voltages:


## $12 \mathrm{~V} \rightarrow 5 \mathrm{~V} \rightarrow 3.3 \mathrm{~V} \rightarrow 2.5 \mathrm{~V} \rightarrow 1.8 \mathrm{~V}$ CD4000 LVC/ALVC/AVC

- Power reduction is one of the keys to progressive growth of integration



## Summary

## TTL

| Logic <br> Family | $\mathrm{T}_{\mathrm{PD}}$ | $\mathrm{T}_{\text {rise/fall }}$ | $\mathrm{V}_{\mathbf{I H}, \text { min }}$ | $\mathrm{V}_{\text {IL,max }}$ | $\mathrm{V}_{\mathrm{OH}, \text { min }}$ | $\mathbf{V}_{\text {OL,max }}$ | Noise <br> Margin |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| (74 ) | 22ns |  | 2.0 V | 0.8 V | 2.4 V | 0.4 V | 0.4 V |
| 74LS | 15ns |  | 2.0 V | 0.8 V | 2.7 V | 0.5 V | 0.3 V |
| 74F | 5ns | 2.3 ns | 2.0 V | 0.8 V | 2.7 V | 0.5 V | 0.3 V |
| 74AS | 4.5ns | 1.5 ns | 2.0 V | 0.8 V | 2.7 V | 0.5 V | 0.3 V |
| 74ALS | 11 ns | 2.3 ns | 2.0 V | 0.8 V | 2.5 V | 0.5 V | 0.3 V |
| ECL | 1.45 ns | 0.35 ns | $-1.165 \mathrm{~V}$ | -1.475V | -1.025V | -1.610V | 0.135 V |
| ( $\overline{40} \overline{0} 0{ }^{-}$ | 250ns | 90ns | 3.5 V | 1.5 V | 4.95 V | 0.05 V | 1.45 V |
| 74 C | 90ns |  | 3.5 V | 1.5 V | 4.5 V | 0.5 V | 1 V |
| 74HC I | 18 ns | 3.6 ns | 3.5 V | 1.0 V | 4.9 V | 0.1 V | 0.9 V |
| 74HCT | 23 ns | 3.9 ns | 2.0 V | 0.8 V | 4.9 V | 0.1 V | 0.7 V |
| 74 AC - | 9ns | 1.5 ns | 3.5 V | 1.5 V | 4.9 V | 0.1 V | 1.4 V |
| 74 ACT , | 9ns | 1.5 ns | 2.0 V | 0.8 V | 4.9 V | 0.1 V | 0.7 V |
| 74 AHC - | 3.7 ns |  | 3.85 V | 1.65 V | 4.4 V | 0.44 V | 0.55 V |
|  |  |  |  |  |  |  |  |
| CMOS |  |  |  |  |  |  |  |

## Exercise F-1

Show that the following circuit works as a demodulator of frequency modulation (FM) signal (quadrature demodulator).


Here the phase shifter gives the shift proportional to the frequency difference between input and the career frequency $\omega_{0}$. The shift at $\omega_{0}$ is $\pi / 2$ as shown in
 the right (this can be achieved with resonant circuits). The low-pass filter cuts components with frequencies as high as $\omega_{0}$.
(hint) Assume the original signal $f(t)$ is much slower than the carrier $A \cos \left(\omega_{0} t\right)$. Then the input can be approximated as

$$
s(t)=A \cos \left\{\left[\omega_{0}+k_{f} f(t)\right] t\right\}
$$

Then the phase shifter output is

$$
q_{\mathrm{ps}}(t)=A \sin \left\{\left[\omega_{0}+k_{f} f(t)\right] t-a k_{f} f(t)\right\}
$$

Taking product and high-frequency filtering gives ... (use $a k_{f} f(t) \ll 1$ ).

In the following phase lock loop (PLL) circuit, the initial $(t=0)$ oscillation frequency of voltage-controlled oscillator (VCO) $\omega$ deviates from $N \omega_{0}$ by $\Delta \omega$. Obtain the relaxation time of $\omega$ to $N \omega_{0}$.

(hint) Here we can put $\theta_{i}=0$ hence input $=V_{i} \sin \omega_{0} t$ without loosing generality. Similarly output $=V_{o} \sin \left[N \omega_{0} t+\theta_{o}(t)\right]$. Now $\omega=N \omega_{0}+d \theta_{o} / d t$ and it is easy to write $d \theta_{o} / d t$ with $A$, $G_{p}, V_{c}, \theta_{o}(t)$ and a constant.

Solve the difference equation below with z-transform.

$$
\begin{cases}x(n)-2 x(n-1)=n & (n \geq 0) \\ x(n)=0 & (n<0)\end{cases}
$$

(hint) z -transform of $n$ is $\frac{z}{(z-1)^{2}}$ as in the table (slide no.14).
Then z-transform of $x(n): X(z)$ is easily obtained. Inverse ztransform gives $x(n)$.

Answer sheet submission deadline: $11^{\text {th }}$ Jan. 2017.

